

**Solutions to the Multivariable Calculus and Linear Algebra problems on the
Comprehensive Examination of February 1, 2013**

Each question is worth 10 points, totaling 80 points.

1. Evaluate the following integrals:

- (a) $\iint_R (x + y) dy dx$, where R is the top half of the circle of radius 2 centered at the origin.

Solution: In polar coordinates, $R = \{(r, \theta) \mid 0 \leq r \leq 2, 0 \leq \theta \leq \pi\}$. Then

$$\begin{aligned} \iint_R (x + y) dy dx &= \int_0^\pi \int_0^2 (r \cos \theta + r \sin \theta) r dr d\theta \\ &= \int_0^\pi \int_0^2 (\cos \theta + \sin \theta) r^2 dr d\theta \\ &= \int_0^\pi (\cos \theta + \sin \theta) \left[\frac{r^3}{3} \right]_0^2 d\theta \\ &= \frac{8}{3} \int_0^\pi (\cos \theta + \sin \theta) d\theta \\ &= \frac{8}{3} \left[\sin \theta - \cos \theta \right]_0^\pi \\ &= \frac{8}{3} ((\sin \pi - \cos \pi) - (\sin 0 - \cos 0)) \\ &= \frac{8}{3} ((0 - (-1)) - (0 - 1)) = \frac{16}{3}. \end{aligned}$$

- (b) $\int_C (2xy + \tan(x^3)) dx + (x^2 + 2xy) dy$, where C is the closed curve that begins at $(0, 0)$, then follows $y = x^2$ to $(1, 1)$, next follows $y = 1$ to $(0, 1)$, and finally follows $x = 0$ back to $(0, 0)$.

Solution: We could divide the piecewise-smooth curve C into its three smooth segments and calculate the integral piece by piece, but it is far easier to use Green's Theorem. Let $P = 2xy + \tan(x^3)$ and $Q = x^2 + 2xy$. Then we have

$$\frac{\partial Q}{\partial x} - \frac{\partial P}{\partial y} = (2x + 2y) - 2x = 2y.$$

We may express the region bounded by C as $R = \{(x, y) \mid 0 \leq x \leq 1, x^2 \leq y \leq 1\}$. Then by Green's Theorem,

$$\int_C P dx + Q dy = \iint_R 2y dA = \int_0^1 \int_{x^2}^1 2y dy dx$$

$$\begin{aligned}
&= \int_0^1 [y^2]_{x^2}^1 dx \\
&= \int_0^1 (1 - x^4) dx \\
&= x - \frac{x^5}{5} \Big|_0^1 = \frac{4}{5}.
\end{aligned}$$

2. Compute the volume of the 3-dimensional region that lies above the paraboloid $z = x^2 + y^2$ and inside the sphere $x^2 + y^2 + z^2 = 2$. Hint: Try cylindrical coordinates.

Solution: The surfaces $z = x^2 + y^2$ and $x^2 + y^2 + z^2 = 2$ intersect where $z + z^2 = 2$, so $0 = z^2 + z - 2 = (z - 1)(z + 2)$. Since $z = x^2 + y^2$ cannot be negative, we have $z = 1$. In cylindrical coordinates the paraboloid is $z = r^2$, and the sphere is $r^2 + z^2 = 2$, or $z = \sqrt{2 - r^2}$. Thus we may express the region as

$$E = \{(r, \theta, z) \mid 0 \leq \theta \leq 2\pi, 0 \leq r \leq 1, r^2 \leq z \leq \sqrt{2 - r^2}\}.$$

Therefore the volume is

$$\begin{aligned}
V &= \iiint_E dV = \int_0^{2\pi} \int_0^1 \int_{r^2}^{\sqrt{2-r^2}} r dz dr d\theta \\
&= 2\pi \int_0^1 (r\sqrt{2-r^2} - r^3) dr \\
&= 2\pi \left[-\frac{1}{3} (2-r^2)^{\frac{3}{2}} - \frac{1}{4} r^4 \right]_0^1 \\
&= 2\pi \left(\left(-\frac{1}{3} - \frac{1}{4} \right) - \left(-\frac{1}{3} \cdot 2^{3/2} - 0 \right) \right) \\
&= \frac{8\sqrt{2} - 7}{6} \pi.
\end{aligned}$$

3. Consider the function

$$f(x, y) = \begin{cases} \frac{x^4}{x^2 + y^2} & \text{if } (x, y) \neq (0, 0), \\ 0 & \text{if } (x, y) = (0, 0). \end{cases}$$

- (a) Show that f is continuous at $(0, 0)$.

Solution: Recall that f is continuous at $(0, 0)$ iff $\lim_{(x,y) \rightarrow (0,0)} f(x, y) = f(0, 0)$. In polar coordinates, $x = r \cos \theta$, $y = r \sin \theta$, and $(x, y) \rightarrow (0, 0)$ becomes $r \rightarrow 0$. Then

$$\lim_{(x,y) \rightarrow (0,0)} \frac{x^4}{x^2 + y^2} = \lim_{r \rightarrow 0} \frac{r^4 \cos^4 \theta}{r^2} = \lim_{r \rightarrow 0} r^2 \cos^4 \theta = 0,$$

where the last equality follows since $r^2 \rightarrow 0$ and $\cos^4 \theta - \sin^4 \theta$ is bounded.

(b) Find $f_x(0, 0)$ and $f_y(0, 0)$.

Solution: We use the definition of partial derivatives.

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{\frac{h^4}{h^2+0} - 0}{h} = \lim_{h \rightarrow 0} h = 0,$$

and

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{0}{h} = 0.$$

4. Find the maximum and minimum values of the function $f(x, y) = x^2 + 4y$ subject to the constraint $x^2 + 2y^2 = 8$.

Solution: Let $g(x, y) = x^2 + 2y^2$. Then we need to find values of x , y and λ such that $\nabla f = \lambda \nabla g$ and $g(x, y) = 8$. We have the following system of equations:

$$2x = \lambda(2x), \quad 4 = \lambda(4y), \quad x^2 + 2y^2 = 8.$$

Writing the first equation as $2x(1 - \lambda) = 0$ yields either $x = 0$ or $\lambda = 1$. When $x = 0$, the third equation yields $y = \pm 2$; when $\lambda = 1$, the second equation yields $y = 1$, so the third equation gives $x = \pm\sqrt{6}$. Thus we get the points $(x, y) = (0, \pm 2), (\pm\sqrt{6}, 1)$. Then we compute

$$f(0, 2) = 8, \quad f(0, -2) = -8, \quad f(\pm\sqrt{6}, 1) = 10.$$

We conclude the maximum value of f is 10 at $(\pm\sqrt{6}, 1)$ and the minimum value of f is -8 at $(0, -2)$.

5. Let A be a 5×7 matrix with real entries. Answer the following questions about A and briefly justify your answers:

(a) Show that the nullspace of A has dimension at least 2.

Solution: By the rank/nullity theorem,

$$\text{rank } A + \text{nullity } A = \text{the number of columns of } A = 7.$$

The nullity of A is the dimension of its nullspace, and the rank of A is equal to its maximum number of linearly independent rows. Since A has 7 columns and 5 rows, the rank is at most 5, so its nullity is at least $7 - 5 = 2$ (because A may have fewer than 5 linearly independent rows).

(b) Assume that the nullspace has dimension exactly 2. What does this imply about the column space of A ?

Solution: For reasons given above we know that $\text{rank } A = 5$. Thus we also know that the dimension of the column space of A is 5. This means that five of the column vectors of A are linearly independent and form a basis of the column space of A . Further, since the column space of A is a 5-dimensional subspace of \mathbb{R}^5 , we can conclude that the column space of A is all of \mathbb{R}^5 .

6. Let U and W be subspaces of a vector space V . Define

$$U + W = \{u + w \mid u \in U, w \in W\}.$$

(a) Prove that $U + W$ is a subspace of V .

Solution: To prove that $U + W$ is a subspace, we must show that it is (1) nonempty, (2) closed under addition, and (3) closed under scalar multiplication. For (1), since U and W both contain $\vec{0}$, so does $U + W$ and so $U + W$ is nonempty; (2) Let $\vec{v}_1, \vec{v}_2 \in U + W$. Then $\vec{v}_1 = \vec{u}_1 + \vec{w}_1$ and $\vec{v}_2 = \vec{u}_2 + \vec{w}_2$, where $\vec{u}_1, \vec{u}_2 \in U$ and $\vec{w}_1, \vec{w}_2 \in W$. So

$$\vec{v}_1 + \vec{v}_2 = (\vec{u}_1 + \vec{w}_1) + (\vec{u}_2 + \vec{w}_2) = (\vec{u}_1 + \vec{u}_2) + (\vec{w}_1 + \vec{w}_2).$$

But $\vec{u}_1 + \vec{u}_2 \in U$ because U is a subspace, and similarly $\vec{w}_1 + \vec{w}_2 \in W$. Thus $\vec{v}_1 + \vec{v}_2 \in U + W$, so $U + W$ is closed under addition;

(3) Let k be a scalar. Then $k\vec{v}_1 = k(\vec{u}_1 + \vec{w}_1) = k\vec{u}_1 + k\vec{w}_1$. But $k\vec{u}_1 \in U$ and $k\vec{w}_1 \in W$, so $k\vec{v}_1 \in U + W$, so $U + W$ is closed under scalar multiplication.

(b) For the vector space \mathbb{R}^2 , give an explicit example of subspaces $U \subseteq \mathbb{R}^2$ and $W \subseteq \mathbb{R}^2$ such that $U \cup W$ is not a subspace of \mathbb{R}^2 . Justify your reasoning.

Solution: There are many solutions to this problem. Here is one. Let $U = \text{Span}\{(1, 0)\}$ be the x -axis and $W = \text{Span}\{(0, 1)\}$ be the y -axis. Being spans, U and W are subspaces of \mathbb{R}^2 . Then $(1, 0), (0, 1) \in U \cup W$, but

$$(1, 0) + (0, 1) = (1, 1) \notin U \cup W.$$

So $U \cup W$ is not closed under addition and is therefore not a subspace of \mathbb{R}^2 .

7. Consider the matrix

$$A = \begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix}.$$

(a) Determine the eigenvalues of A and a basis of each eigenspace of A .

Solution: The eigenvalues of A are the roots of its characteristic polynomial

$$\begin{aligned} \det(A - \lambda I_3) &= \det \left(\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) = \det \begin{bmatrix} 1 - \lambda & 1 & 1 \\ 1 & 1 - \lambda & 1 \\ 0 & 0 & -\lambda \end{bmatrix} \\ &= -\lambda \det \begin{bmatrix} 1 - \lambda & 1 \\ 1 & 1 - \lambda \end{bmatrix} = -\lambda((1 - \lambda)^2 - 1) \\ &= -\lambda(1 - 2\lambda + \lambda^2 - 1) = -\lambda(-2\lambda + \lambda^2) = -\lambda^2(\lambda - 2). \end{aligned}$$

Hence the characteristic polynomial has two roots: $\lambda = 0$ and $\lambda = 2$, which are the two eigenvalues of A .

Next we compute the corresponding eigenvectors.

$\lambda = 0$: The eigenspace is the solution space of $(A - 0I)\vec{x} = \vec{0}$. Being homogeneous, we need only row reduce the coefficient matrix:

$$\begin{bmatrix} 1 & 1 & 1 \\ 1 & 1 & 1 \\ 0 & 0 & 0 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 1 & 1 \\ 0 & 0 & 0 \\ 0 & 0 & 0 \end{bmatrix},$$

so we have one equation: $x_1 + x_2 + x_3 = 0$. Thus x_2 and x_3 are free variables. Solving for x_1 gives $x_1 = -x_2 - x_3$, so the general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} -x_2 - x_3 \\ x_2 \\ x_3 \end{bmatrix} = x_2 \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix} + x_3 \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix}.$$

Therefore, the eigenspace of A associated to $\lambda = 0$ has basis $\left\{ \begin{bmatrix} -1 \\ 1 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ 1 \end{bmatrix} \right\}$.

$\lambda = 2$: Row reducing the coefficient matrix of $(A - 2I)\vec{x} = \vec{0}$ gives

$$\begin{bmatrix} -1 & 1 & 1 \\ 1 & -1 & 1 \\ 0 & 0 & -2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & -1 & 0 \\ 0 & 0 & 1 \\ 0 & 0 & 0 \end{bmatrix},$$

which gives the system $x_1 - x_2 = x_3 = 0$ with free variable x_2 . The solutions are

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \end{bmatrix} = \begin{bmatrix} x_2 \\ x_2 \\ 0 \end{bmatrix} = x_2 \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix}.$$

Thus the eigenspace of A associated to $\lambda = 2$ has basis $\left\{ \begin{bmatrix} 1 \\ 1 \\ 0 \end{bmatrix} \right\}$.

(b) Is A diagonalizable? Explain your reasoning.

Solution: A is diagonalizable because it is a 3×3 matrix and has three linearly independent eigenvectors.

8. Let $T : V \rightarrow W$ be a linear transformation from the vector space V to the vector space W . Assume that $v_1, \dots, v_n \in V$ have the property that $T(v_1), \dots, T(v_n)$ are linearly independent.

(a) Prove that v_1, \dots, v_n are also linearly independent.

Solution: We aim to prove that the only linear combination of $\vec{v}_1, \dots, \vec{v}_n$ that equals $\vec{0}_V$ is the trivial one with all coefficients equal to zero. Suppose $c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}_V$. Because T is a linear transformation,

$$c_1\vec{v}_1 + c_2\vec{v}_2 + \dots + c_n\vec{v}_n = \vec{0}_V \quad \Rightarrow$$

$$\begin{aligned}
T(c_1\vec{v}_1 + c_2\vec{v}_2 + \cdots + c_n\vec{v}_n) = \vec{0}_W &\Rightarrow \\
T(c_1\vec{v}_1) + T(c_2\vec{v}_2) + \cdots + T(c_n\vec{v}_n) = \vec{0}_W &\Rightarrow \\
c_1T(\vec{v}_1) + c_2T(\vec{v}_2) + \cdots + c_nT(\vec{v}_n) = \vec{0}_W &\Rightarrow \\
c_1 = \cdots = c_n = 0, &
\end{aligned}$$

where the last implication follows since $T(\vec{v}_1), \dots, T(\vec{v}_n)$ are linearly independent.

- (b) Assume in addition that v_1, \dots, v_n span V . Prove that T is one-to-one (injective).

Solution: By a standard theorem in linear algebra, it suffices to prove that the null space of T consists of only the zero vector. So take $\vec{u} \in V$ such that $T(\vec{u}) = \vec{0}_W$. Since $\vec{v}_1, \dots, \vec{v}_n$ span V , we can write $\vec{u} = c_1\vec{v}_1 + \cdots + c_n\vec{v}_n$. Then

$$\vec{0}_W = T(\vec{u}) = T(c_1\vec{v}_1 + \cdots + c_n\vec{v}_n) = c_1T(\vec{v}_1) + \cdots + c_nT(\vec{v}_n),$$

so that $c_1 = \cdots = c_n = 0$ since $T(\vec{v}_1), \dots, T(\vec{v}_n)$ are linearly independent. It follows that $\vec{u} = 0 \cdot \vec{v}_1 + \cdots + 0 \cdot \vec{v}_n = \vec{0}_V$, and one-to-one follows.