

**Solutions to the Multivariable Calculus and Linear Algebra problems on the  
Comprehensive Examination of January 30, 2015**

There are 9 problems (10 points each, totaling 90 points) on this portion of the examination.  
**Show all of your work.**

1. Find the critical points of the function  $f(x, y) = x^3 + y^3 - 3xy$  and classify each as a local maximum, local minimum, or a saddle point.

**Solution:** Since  $f$  is a polynomial, we know it is differentiable on  $\mathbb{R}^2$ . The critical points of  $f$  occur when

$$f_x(x, y) = 3x^2 - 3y = 0 \quad \text{and} \quad f_y(x, y) = 3y^2 - 3x = 0.$$

Then we have  $y = x^2$ , and the second equation becomes  $3(x^2)^2 - 3x = 0$ , or  $x(x^3 - 1) = 0$ . Then the real roots are  $x = 0$  or  $x = 1$ , with the corresponding  $y = 0$  and 1, respectively. Therefore the critical points of  $f$  are  $(0, 0)$  and  $(1, 1)$ .

Now we calculate the second derivatives:

$$\begin{aligned} f_{xx} &= 6x & f_{xy} &= -3 & f_{yy} &= 6y \\ D &= f_{xx}f_{yy} - f_{xy}^2 = (6x)(6y) - (-3)^2 = 36xy - 9. \end{aligned}$$

Applying the second derivative test, we see that  $D(0, 0) = -9 < 0$ , so  $(0, 0)$  is a saddle point;  $D(1, 1) = 36 - 9 > 0$  and  $f_{xx}(1, 1) = 6 > 0$ , so  $(1, 1)$  is a local minimum.

2. Let  $C$  be the triangle with vertices  $(0, 0)$ ,  $(1, 1)$ , and  $(0, 1)$ , oriented counterclockwise, and let  $\mathbf{F}(x, y) = \langle xy, x^2 \rangle$ .

- (a) According to Green's theorem, the line integral

$$\int_C \mathbf{F} \cdot d\mathbf{r} = \int_C xy \, dx + x^2 \, dy$$

is equal to a certain double integral. Set up this double integral.

**Solution:** Let  $R$  be the region bound by  $C$ . Then

$$\int_C xy \, dx + x^2 \, dy = \iint_R \frac{\partial}{\partial x} x^2 - \frac{\partial}{\partial y} xy \, dA = \iint_R 2x - x \, dA = \iint_R x \, dA.$$

- (b) Verify Green's Theorem in this case by evaluating both the line integral and the double integral of part (a).

**Solution:** *Line integral:* First it is necessary to parametrize the three segments of  $C$ .

$$C_1 : x = t, y = t \Rightarrow dx = dt, dy = dt, 0 \leq t \leq 1$$

$$C_2 : x = 1 - t, y = 1 \Rightarrow dx = -dt, dy = 0 \, dt, 0 \leq t \leq 1$$

$$C_3 : x = 0, y = 1 - t \Rightarrow dx = 0 \, dt, dy = -dt, 0 \leq t \leq 1.$$

Thus

$$\begin{aligned} \int_C xy \, dx + x^2 \, dy &= \int_{C_1} xy \, dx + x^2 \, dy + \int_{C_2} xy \, dx + x^2 \, dy + \int_{C_2} xy \, dx + x^2 \, dy \\ &= \int_0^1 (t^2 + t^2) dt + \int_0^1 ((1-t)(-1) + (1-t)^2(0)) dt \\ &\quad + \int_0^1 (0(1-t)(0) + 0^2(-1)) dt \\ &= \int_0^1 2t^2 + t - 1 \, dt = \left. \frac{2t^3}{3} + \frac{t^2}{2} - t \right|_0^1 = \frac{1}{6}. \end{aligned}$$

*Double integral:* We may express  $R = \{(x, y) \mid 0 \leq x \leq y, 0 \leq y \leq 1\}$ . Then

$$\iint_R x \, dA = \int_0^1 \int_x^1 x \, dy \, dx = \int_0^1 x - x^2 \, dx = \left. \frac{x^2}{2} - \frac{x^3}{3} \right|_0^1 = \frac{1}{2} - \frac{1}{3} = \frac{1}{6}.$$

3. Let

$$f(x, y) = \begin{cases} \frac{x^4 + y^3 + xy}{x^2 + y^2} & \text{if } (x, y) \neq (0, 0), \\ 0 & \text{if } (x, y) = (0, 0). \end{cases}$$

(a) Is  $f$  continuous at  $(0, 0)$ ? Justify your answer.

**Solution:** Recall that  $f$  is continuous at  $(0, 0)$  iff  $\lim_{(x,y) \rightarrow (0,0)} f(x, y) = f(0, 0)$ . Let  $(x, y) \rightarrow (0, 0)$  along  $y = mx$ , where  $m$  is any real number. Then

$$f(x, y) = f(x, mx) = \frac{x^4 + (mx)^3 + x(mx)}{x^2 + (mx)^2} = \frac{x^2(x^2 + m^3x + m)}{x^2(1 + m^2)} = \frac{x^2 + m^3x + m}{m^2 + 1}.$$

Thus  $f(x, y) \rightarrow \frac{m}{m^2+1}$  as  $(x, y) \rightarrow (0, 0)$  along  $y = mx$ , so  $f$  has different limits along different paths. Therefore  $\lim_{(x,y) \rightarrow (0,0)} f(x, y)$  does not exist, and  $f$  is not continuous at  $(0, 0)$ .

(b) Find  $f_x(0, 0)$  and  $f_y(0, 0)$ .

**Solution:** We shall apply the definition of partial derivatives.

$$f_x(0, 0) = \lim_{h \rightarrow 0} \frac{f(h, 0) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h^4/h^2 - 0}{h} = \lim_{h \rightarrow 0} h = 0$$

and

$$f_y(0, 0) = \lim_{h \rightarrow 0} \frac{f(0, h) - f(0, 0)}{h} = \lim_{h \rightarrow 0} \frac{h^3/h^2 - 0}{h} = \lim_{h \rightarrow 0} 1 = 1.$$

4. Find the directional derivative of the function  $f(x, y, z) = x\sqrt{yz+1}$  at the point  $(2, 1, 3)$  in the direction of the vector  $\langle 2, -1, 2 \rangle$ .

**Solution:** The unit vector in the direction of  $\langle 2, -1, 2 \rangle$  is

$$\mathbf{u} = \frac{\langle 2, -1, 2 \rangle}{|\langle 2, -1, 2 \rangle|} = \frac{\langle 2, -1, 2 \rangle}{\sqrt{2^2 + (-1)^2 + 2^2}} = \frac{\langle 2, -1, 2 \rangle}{3} = \left\langle \frac{2}{3}, -\frac{1}{3}, \frac{2}{3} \right\rangle.$$

The directional derivative of  $f$  in the direction of  $\mathbf{u}$  is therefore

$$\begin{aligned} D_{\mathbf{u}}f(x, y, z) &= \nabla f(x, y, z) \cdot \mathbf{u} \\ &= \left\langle \sqrt{yz+1}, \frac{xz}{2\sqrt{yz+1}}, \frac{xy}{2\sqrt{yz+1}} \right\rangle \cdot \left\langle \frac{2}{3}, -\frac{1}{3}, \frac{2}{3} \right\rangle \\ &= \frac{2}{3}\sqrt{yz+1} - \frac{xz}{6\sqrt{yz+1}} + \frac{xy}{3\sqrt{yz+1}}. \end{aligned}$$

Thus

$$\begin{aligned} D_{\mathbf{u}}f(2, 1, 3) &= \frac{2}{3}\sqrt{(1)(3)+1} - \frac{(2)(3)}{6\sqrt{(1)(3)+1}} + \frac{(2)(1)}{3\sqrt{(1)(3)+1}} \\ &= \frac{4}{3} - \frac{1}{2} + \frac{1}{3} = \frac{7}{6}. \end{aligned}$$

5. Find the volume of the region that is inside both the sphere  $x^2 + y^2 + z^2 = 25$  and the cylinder  $x^2 + y^2 = 9$ .

**Solution:** Let  $E$  denote the region in question. In cylindrical coordinates, the cylinder is  $r = 3$ , and the sphere is  $r^2 + z^2 = 25$ . Then  $E = \{(r, \theta, z) \mid 0 \leq \theta \leq 2\pi, 0 \leq r \leq 3, -\sqrt{25-r^2} \leq z \leq \sqrt{25-r^2}\}$ . The volume of  $E$  is therefore

$$\begin{aligned} \iiint_E dV &= \int_0^{2\pi} \int_0^3 \int_{-\sqrt{25-r^2}}^{\sqrt{25-r^2}} r \, dz \, dr \, d\theta \\ &= \int_0^{2\pi} \int_0^3 2r\sqrt{25-r^2} \, dz \, dr \, d\theta \\ &= 2\pi \left[ -\frac{2}{3}(25-r^2)^{3/2} \right]_0^3 \\ &= -\frac{4\pi}{3}((25-3^2)^{3/2} - (25-0^2)^{3/2}) \\ &= -\frac{4\pi}{3}(16^{3/2} - 25^{3/2}) = -\frac{4\pi}{3}(64 - 125) = \frac{244\pi}{3}, \end{aligned}$$

since  $16^{3/2} = (4^2)^{3/2} = 4^3 = 64$  and  $25^{3/2} = (5^2)^{3/2} = 5^3 = 125$ .

6. Let  $T : \mathbb{R}^4 \rightarrow \mathbb{R}^3$  be the linear transformation  $T(\mathbf{x}) = A\mathbf{x}$ , where

$$A = \begin{bmatrix} 1 & -2 & 2 & 7 \\ 2 & -4 & 2 & 8 \\ 1 & -2 & -1 & -2 \end{bmatrix}.$$

- (a) Find a basis for the kernel, or nullspace, of  $T$ .

**Solution:** The kernel consists of the solutions of the homogeneous system  $A\mathbf{x} = \mathbf{0}$ . We first row reduce the matrix  $A$ :

$$\begin{bmatrix} 1 & -2 & 2 & 7 \\ 2 & -4 & 2 & 8 \\ 1 & -2 & -1 & -2 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & -2 & 0 & 1 \\ 0 & 0 & 1 & 3 \\ 0 & 0 & 0 & 0 \end{bmatrix},$$

so we have  $x_1 - 2x_2 + x_4 = x_3 + 3x_4 = 0$  with free variables  $x_2$  and  $x_4$ . The general solution is

$$\begin{bmatrix} x_1 \\ x_2 \\ x_3 \\ x_4 \end{bmatrix} = \begin{bmatrix} 2x_2 - x_4 \\ x_2 \\ -3x_4 \\ x_4 \end{bmatrix} = x_2 \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix} + x_4 \begin{bmatrix} -1 \\ 0 \\ -3 \\ 1 \end{bmatrix}.$$

Thus a basis of the kernel of  $T$  is given by

$$\left\{ \begin{bmatrix} 2 \\ 1 \\ 0 \\ 0 \end{bmatrix}, \begin{bmatrix} -1 \\ 0 \\ -3 \\ 1 \end{bmatrix} \right\}.$$

(b) What is the dimension of the range of  $T$ ?

**Solution:** From part (a) we know  $\dim \ker T = 2$ , and  $\dim \text{domain } T = \text{number of columns of } A = 4$ . So the rank/nullity theorem tells us  $\dim \text{range } T = 4 - 2 = 2$ .

7. Suppose that  $V$  is a vector space and  $\vec{u}$  and  $\vec{v}$  are vectors in  $V$ . Show that

$$\text{Span}(\{3\vec{u} + \vec{v}, \vec{u} - \vec{v}\}) = \text{Span}(\{\vec{u}, \vec{v}\}).$$

**Solution:** Denote  $S_1 = \{3\vec{u} + \vec{v}, \vec{u} - \vec{v}\}$  and  $S_2 = \{\vec{u}, \vec{v}\}$ . In order to show  $\text{Span}(S_1) = \text{Span}(S_2)$ , it suffices to show that

- (1) Every vector in  $S_1$  can be written as a linear combination of the vectors in  $S_2$ , and
- (2) Every vector in  $S_2$  can be written as a linear combination of the vectors in  $S_1$ .

(1) is obvious. (2) is not hard to show, either. We first want to express  $\vec{u}$  as a linear combination  $u = a(3\vec{u} + \vec{v}) + b(\vec{u} - \vec{v})$  for some  $a, b$ . Since  $a(3\vec{u} + \vec{v}) + b(\vec{u} - \vec{v}) = (3a + b)\vec{u} + (a - b)\vec{v}$ , this means picking  $a$  and  $b$  so that

$$3a + b = 1 \quad a - b = 0.$$

One sees easily that the solution is  $a = b = \frac{1}{4}$ . Thus  $\vec{u} = \frac{1}{4}(3\vec{u} + \vec{v}) + \frac{1}{4}(\vec{u} - \vec{v})$ . A similar procedure shows that  $\vec{v} = \frac{1}{4}(3\vec{u} + \vec{v}) - \frac{3}{4}(\vec{u} - \vec{v})$ .

8. Let

$$A = \begin{bmatrix} 5 & 0 & 0 \\ 0 & 1 & 2 \\ 1 & 2 & 4 \end{bmatrix}.$$

(a) Find all eigenvalues of  $A$ .

**Solution:** The eigenvalues of  $A$  are the roots of its characteristic polynomial

$$\begin{aligned} \det(A - \lambda I_3) &= \det \left( \begin{bmatrix} 5 & 0 & 0 \\ 0 & 1 & 2 \\ 1 & 2 & 4 \end{bmatrix} - \lambda \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 0 \\ 0 & 0 & 1 \end{bmatrix} \right) = \det \begin{bmatrix} 5 - \lambda & 0 & 0 \\ 0 & 1 - \lambda & 2 \\ 1 & 2 & 4 - \lambda \end{bmatrix} \\ &= (5 - \lambda) \det \begin{bmatrix} 1 - \lambda & 2 \\ 2 & 4 - \lambda \end{bmatrix} = (5 - \lambda)((1 - \lambda)(4 - \lambda) - 4) \\ &= (5 - \lambda)(4 - 5\lambda + \lambda^2 - 4) = -\lambda(\lambda - 5)^2. \end{aligned}$$

Thus  $A$  has two eigenvalues:  $\lambda = 0$  and  $\lambda = 5$ .

- (b) Find, if possible, an invertible matrix  $P$  such that  $P^{-1}AP$  is diagonal, or show that no such matrix exists.

**Solution:** The existence of  $P$  is equivalent to saying that  $3 \times 3$  matrix  $A$  is diagonalizable, i.e., has three linearly independent eigenvectors. The theory of eigenspaces provides the tools needed to decide whether or not  $A$  is diagonalizable:

- The dimension of each eigenspace is bounded by the multiplicity of the corresponding eigenvalue in the characteristic polynomial. Thus the eigenspace of  $\lambda = 0$  has dimension  $\leq 1$  and the eigenspace of  $\lambda = 5$  has dimension  $\leq 2$ .
- $A$  is diagonalizable  $\iff$  the dimensions of the eigenspaces add up to 3  $\iff$  the dimension of the each eigenspace *equals* the multiplicity of the eigenvalue in the characteristic polynomial.

We begin with  $\lambda = 5$ . The eigenspace is the solution space of  $(A - 5I_3)\mathbf{x} = \mathbf{0}$ . Being homogeneous, we need only row reduce the coefficient matrix:

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & -4 & 2 \\ 1 & 2 & -1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{bmatrix},$$

which has rank 2. By the rank-nullity theorem, the dimension of the nullspace (= the eigenspace of 5) is  $3 - 2 = 1$ . This is strictly smaller than 2, which is the multiplicity of 5 as a root of the characteristic polynomial. Hence  $A$  is not diagonalizable, and no such matrix  $P$  exists.

**Alternate Solution:** The existence of  $P$  is equivalent to saying that  $3 \times 3$  matrix  $A$  is diagonalizable, i.e., has three linearly independent eigenvectors. We compute the dimensions of the eigenspaces.

$\lambda = 5$ . The eigenspace is the solution space of  $(A - 5I_3)\mathbf{x} = \mathbf{0}$ . Being homogeneous, we need only row reduce the coefficient matrix:

$$\begin{bmatrix} 0 & 0 & 0 \\ 0 & -4 & 2 \\ 1 & 2 & -1 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & -1/2 \\ 0 & 0 & 0 \end{bmatrix},$$

which has rank 2. By the rank-nullity theorem, the dimension of the nullspace (= the eigenspace of 5) is  $3 - 2 = 1$ . Hence there is only one linearly independent eigenvector when  $\lambda = 5$ .

$\lambda = 0$ . The eigenspace is the solution space of  $(A - 0I_3)\mathbf{x} = A\mathbf{x} = \mathbf{0}$ . Being homogeneous, we need only row reduce the coefficient matrix:

$$\begin{bmatrix} 5 & 0 & 0 \\ 0 & 1 & 2 \\ 1 & 2 & 4 \end{bmatrix} \longrightarrow \begin{bmatrix} 1 & 0 & 0 \\ 0 & 1 & 2 \\ 0 & 0 & 0 \end{bmatrix},$$

which has rank 2. By the rank-nullity theorem, the dimension of the nullspace (= the eigenspace of 0) is  $3 - 2 = 1$ . Hence there is only one linearly independent eigenvector when  $\lambda = 0$ .

It follows that there are only two linearly independent eigenvectors. So  $A$  is not diagonalizable, and no such matrix  $P$  exists.

9. Let  $V$  be the vector space of polynomials of degree at most 2, and let

$$\mathcal{B} = \{1, x + 1, x^2 + x + 1\},$$

which is a basis for  $V$ . Suppose that  $T : V \rightarrow V$  is a linear transformation, and that the matrix of  $T$  relative to  $\mathcal{B}$  is

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 0 & -1 \\ 2 & 5 & 1 \end{bmatrix}.$$

Find  $T(3x^2 + x + 2)$ .

**Solution:** We first compute the coordinate vector of  $3x^2 + x + 2$  relative to  $\mathcal{B}$ . Since

$$\begin{aligned} 3x^2 + x + 2 &= 3(x^2 + x + 1) - 2x - 1 = 3(x^2 + x + 1) - 2(x + 1) + 1 \\ &= 1(1) - 2(x + 1) + 3(x^2 + x + 1), \end{aligned}$$

the coordinate vector of  $3x^2 + x + 2$  is  $\begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix}$ . The coordinate vector of  $T(3x^2 + x + 2)$

relative to  $\mathcal{B}$  is therefore

$$\begin{bmatrix} 1 & 2 & 3 \\ 3 & 0 & -1 \\ 2 & 5 & 1 \end{bmatrix} \begin{bmatrix} 1 \\ -2 \\ 3 \end{bmatrix} = \begin{bmatrix} 6 \\ 0 \\ -5 \end{bmatrix}.$$

So  $T(3x^2 + x + 2) = 6(1) + 0(x + 1) + (-5)(x^2 + x + 1) = -5x^2 - 5x + 1$ .