

Higher differential geometry and symplectic structures

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Amherst, Gone Fishing, March. 19 2023

Higher categorical structures

▶ Alan Weinstein 80's Birthday Conference in Paris Jun 19-23

▶ Dorothea Schlözer female postdoc program, deadline April 15th

- Source: theoretical physics needs to go to higher dimensions (3+1 dimension). For example, very roughly, higher dim. TQFT is a higher functor from the higher category of higher-cobordisms to that of higher-vector spaces.
- Lurie, Toen et al.: higher structures in algebraic geometry (around 00's) absorbs homotopy theory and category theory. It is very universal however also rather abstract.
- Baez et al., Poisson community, Stolz-Teichner program: higher structures in differential geometry. It involves more concrete models and more direct relation to math physics.

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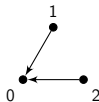
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1 •

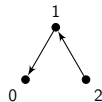
$$\hat{\mathcal{A}}^1(X) = X_0,$$

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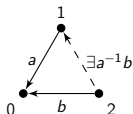
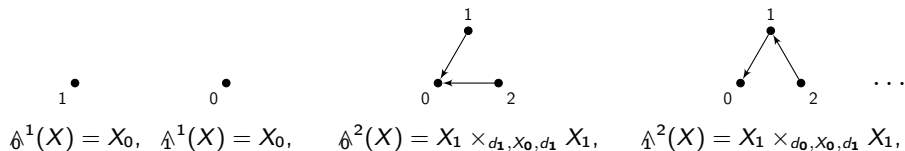


$$\hat{\mathcal{A}}^2(X) = X_1 \times_{d_1, X_0, d_1} X_1,$$

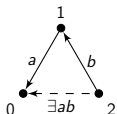


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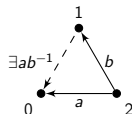
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

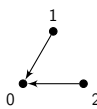
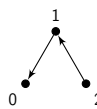
Kan(2, 0)



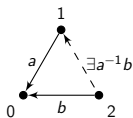
Kan(2, 1)



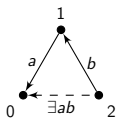
Kan(2, 2)

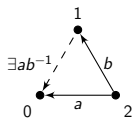
$\hat{\Delta}^1(X) = X_0$, $\hat{\Delta}^1(X) = X_0$, $\hat{\Delta}^2(X) = X_1 \times_{d_1, X_0, d_1} X_1$, $\hat{\Delta}^2(X) = X_1 \times_{d_0, X_0, d_1} X_1$, ...



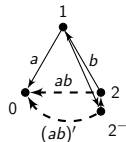
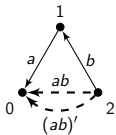
Kan(2, 0)



Kan(2, 1)



Kan(2, 2)



Kan(3, 1)

incomplete Category of fibrant objects (i.C.F.O.)

Let \mathcal{C} be a category with finite products and terminal object $* \in \mathcal{C}$ equipped with two distinguished classes of morphisms called **weak equivalences** and **fibrations**. A morphism which is both a weak equivalence and a fibration is called an **acyclic fibration**. We say \mathcal{C} is an **category of fibrant objects (CFO)** iff:

- 1 Every isomorphism in \mathcal{C} is an acyclic fibration.
- 2 The class of weak equivalences satisfy “2 out of 3”.
- 3 The composition of two fibrations is a fibration.
- 4 If the pullback along a fibration exists, then it is a fibration.
- 5 The pullback along an acyclic fibration exists, and is an acyclic fibration.
- 6 For any object $X \in \mathcal{C}$ there exists a (not necessarily functorial) **path object**.
- 7 All objects of \mathcal{C} are **fibrant**. That is, for any $X \in \mathcal{C}$ the unique map $X \rightarrow *$ is a fibration.

incomplete Category of fibrant objects (i.C.F.O.)

Let \mathcal{C} be a category with finite products and terminal object $* \in \mathcal{C}$ equipped with two distinguished classes of morphisms called **weak equivalences** and **fibrations**. A morphism which is both a weak equivalence and a fibration is called an **acyclic fibration**. We say \mathcal{C} is an **incomplete category of fibrant objects (iCFO)** iff:

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- 2 The class of weak equivalences satisfy “2 out of 3”.
- 3 The composition of two fibrations is a fibration.
- 4 If the pullback along a fibration exists, then it is a fibration. That is, if $Y \xrightarrow{g} Z \xleftarrow{f} X$ is a diagram in \mathcal{C} with f a fibration, **and if $X \times_Z Y$ exists**, then the induced projection $X \times_Z Y \rightarrow Y$ is a fibration.
- 5 The pullback along an acyclic fibration exists, and is an acyclic fibration. That is, if $Y \xrightarrow{g} Z \xleftarrow{f} X$ is a diagram in \mathcal{C} with f an acyclic fibration, then the pullback $X \times_Z Y$ exists, and the induced projection $X \times_Z Y \rightarrow Y$ is an acyclic fibration.
- 6 For any object $X \in \mathcal{C}$ there exists a (not necessarily functorial) **path object**

Lemma (Brown's factorization Lemma for iCFO, Rogers-Zhu'20)

If \mathcal{C} is an iCFO and $f : X \rightarrow Y$ is a morphism in \mathcal{C} , then f can be factored as $f = p \circ i$, where p is a fibration, and i is a weak equivalence which is a section (right inverse) of an acyclic fibration.

Lemma (Brown's factorization Lemma for iCFO, Rogers-Zhu'20)

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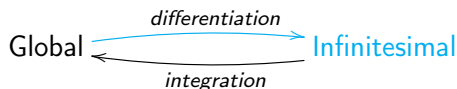
Theorem (Rogers-Zhu'20)

The simplicial localization $L_W\mathcal{C}$ (or underlying ∞ -category) of an iCFO \mathcal{C} has a nice description in terms of the nerves of categories of spans. That is, for all objects $X, Y \in \mathcal{C}$,

$$\mathrm{Hom}_{L_W\mathcal{C}}(X, Y) \leftarrow \mathrm{NSpan}_{w.e.}(X, Y) \leftarrow \mathrm{NSpan}_{acyc.}(X, Y)$$

are weak equivalence of simplicial sets.

Integration v.s. Differentiation



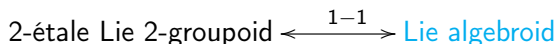
Getzler'04



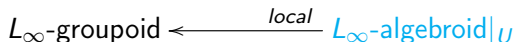
Henriques'06



Tseng-Zhu'06



Ševera-Širaň'20



LFWRZ (now)



Differential Forms on X .

$$\begin{array}{ccccccc} & \vdots & & \vdots & & \vdots & \\ & \uparrow & & \uparrow & & \uparrow & \\ & \delta & & \delta & & \delta & \\ \Omega^0(X_2) & \xrightarrow{d} & \Omega^1(X_2) & \xrightarrow{d} & \Omega^2(X_2) & \xrightarrow{d} & \dots \\ & \uparrow & & \uparrow & & \uparrow & \\ \Omega^0(X_1) & \xrightarrow{d} & \Omega^1(X_1) & \xrightarrow{d} & \Omega^2(X_1) & \xrightarrow{d} & \dots \\ & \uparrow & & \uparrow & & \uparrow & \\ \Omega^0(X_0) & \xrightarrow{d} & \Omega^1(X_0) & \xrightarrow{d} & \Omega^2(X_0) & \xrightarrow{d} & \dots \end{array}$$

Normalised Differential Forms on X_\bullet

$$\begin{array}{ccccccc} & \vdots & & \vdots & & \vdots & \\ & \uparrow & & \uparrow & & \uparrow & \\ & \delta & & \delta & & \delta & \\ \hat{\Omega}^0(X_2) & \xrightarrow{d} & \hat{\Omega}^1(X_2) & \xrightarrow{d} & \hat{\Omega}^2(X_2) & \xrightarrow{d} & \dots \\ & \uparrow & & \uparrow & & \uparrow & \\ \hat{\Omega}^0(X_1) & \xrightarrow{d} & \hat{\Omega}^1(X_1) & \xrightarrow{d} & \hat{\Omega}^2(X_1) & \xrightarrow{d} & \dots \\ & \uparrow & & \uparrow & & \uparrow & \\ \hat{\Omega}^0(X_0) & \xrightarrow{d} & \hat{\Omega}^1(X_0) & \xrightarrow{d} & \hat{\Omega}^2(X_0) & \xrightarrow{d} & \dots \end{array}$$

$\omega \in \hat{\Omega}^k(X_i)$ iff $s_i^* \omega = 0$ for all $i = 0, \dots, k$.

For $x \in X_0$, $v \in \mathcal{T}_l(X_\bullet)_x$, $w \in \mathcal{T}_{m-l}(X_\bullet)_x$,

$$\lambda_x^{\omega_\bullet}(v, w) := \sum_{\sigma \in \text{Sf}_{k, m-k}} (-1)^\sigma \omega_m(T(s_{\sigma(m-1)} \cdots s_{\sigma(k)})v, T(s_{\sigma(k-1)} \cdots s_{\sigma(0)})w)$$

where $\text{Sf}_{k, m-k}$ is the set of $(k, m-k)$ -shuffles, and $(-1)^\sigma$ is the permutation sign of σ .

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- λ^{ω_\bullet} is graded anti-symmetric;
- λ^{ω_\bullet} is infinitesimally multiplicative, that is,

$$\lambda^{\alpha_\bullet}(\partial u, w) + (-1)^{k+1} \lambda^{\alpha_\bullet}(u, \partial w) = 0.$$

I.M. forms and shifted symplectic forms

For $x \in X_0$, $v \in \mathcal{T}_l(X_\bullet)_x$, $w \in \mathcal{T}_{m-l}(X_\bullet)_x$,

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Definition

A m -shifted symplectic form on a Lie n -groupoid is a non-degenerate, closed m -shifted 2-form.

Examples for small m, n

$n \backslash m$	0	1	2
0	Symp. Mfd.		
1	Symp. Stack	integrable Dirac Mfd.	BG
2		non-int Dirac Mfd.	Courant algebroid

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2		Quasi Symp. stacky Gpd.	Courant algebroid

Definition (Cueca-Zhu'23)

Morita Equivalence of Lie n -groupoids X_\bullet and Y_\bullet is given by

$$X_\bullet \xleftarrow{f_\bullet} Z_\bullet \xrightarrow{g_\bullet} Y_\bullet$$

where f_\bullet and g_\bullet are acyclic fibrations (also called hypercovers defined in iCFO).

Definition (Cueca-Zhu'23)

Symplectic Morita Equivalence of m -shifted symplectic Lie n -groupoids $(X_\bullet, \alpha_\bullet)$ and $(Y_\bullet, \beta_\bullet)$ is given by

$$(X_\bullet, \alpha_\bullet) \xleftarrow{f_\bullet} (Z_\bullet, \phi_\bullet) \xrightarrow{g_\bullet} (Y_\bullet, \beta_\bullet)$$

where f_\bullet and g_\bullet are acyclic fibrations (also called hypercovers defined in iCFO). Moreover, ϕ_\bullet is a $m - 1$ -shifted form and $f_\bullet^* \alpha_\bullet - g_\bullet^* \beta_\bullet = D\phi_\bullet$.

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Theorem (Cueca-Zhu'23)

When $m = n = 1$, this symplectic Morita Equivalence coincides with the one defined in Xu'04 via Hamiltonian bimodules.

BG as 2-shifted symplectic stack

Theorem (Cueca-Zhu'23)

The 2-shifted symplectic stack BG has the following symplectic Morita Equivalent models

$$\begin{array}{ccc} \bullet \longleftarrow (G, 1/2\Theta) & \longleftarrow & (G \times G, 1/2\Omega) \dots \\ & \uparrow \text{ev}_1 & \uparrow \text{ev}_2 \\ \bullet \longleftarrow (PG, \omega) & \longleftarrow & \Omega G \dots \\ & \downarrow \text{id} & \downarrow \text{id} \\ \bullet \longleftarrow PG & \longleftarrow & (\Omega G, \omega) \dots \end{array}$$

where $\Theta \in \Omega^3(G)$ is the Cartan 3-form, $\Omega \in \Omega^2(G \times G)$ is the Brylinski-Weinstein 2-form, and ω is the Segal's 2-form.

Definition (Zhu'09)

A simplicial morphism $f_\bullet : X_\bullet \rightarrow Y_\bullet$ is a **acyclic fibration** or **hypercover** if the maps

$$((d_0, \dots, d_i), f_i) : X_i \rightarrow \partial_i(X_\bullet) \times_{\partial_i(Y_\bullet)} Y_i = \text{Hom}(\partial\Delta[i] \rightarrow \Delta[i], X_\bullet \rightarrow Y_\bullet)$$

are surjective submersions for $0 \leq i < n$ and an isomorphism for $i = n$.

Acyclic Fibration, Weak Equivalence

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are surjective submersions for $0 \leq i < n$ and an isomorphism for $i = n$.

Definition (Behrend-Getzler'18, Rogers-Zhu'20)

A simplicial morphism $f_\bullet : X_\bullet \rightarrow Y_\bullet$ is a **weak equivalence** if

$$r_i : \text{Hom}(\Delta[i] \rightarrow \Delta[i+1], X_\bullet \rightarrow Y_\bullet) \rightarrow \text{Hom}(\partial\Delta[i] \rightarrow \Lambda[i+1, i+1], X_\bullet \rightarrow Y_\bullet)$$

is a surjective submersion for $i < n$ and isomorphism for $i \geq n$.

Integration:

- L_∞ -algebras by Henriques'08,
- nilpotent L_∞ -algebras by Getzler'09,
- L_∞ -algebroids (local result) by Ševera-Širaň'20

Differentiation:

- A formalization of the notion Lie differentiation in higher geometry has been given by Lurie (deformation context), worked out in diff. Geom. setting by Joost Nuiten, but the result is abstract.
- Ševera sketches an explicit differentiation functor with an idea inspired by Konsevich 2006. But the result is only a presheaf.
- Differentiation to tangent complex [Fernandes-Li-Ryvkin-Wessel-Zhu].